

CURRICULUM VITAE - Dr. Veljko Potkonjak

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PERSONAL

Name: **Veljko N. Potkonjak**

Born: July 25, 1951. Lives in Belgrade, Serbia.

Current Academic Rank: Professor

Primary Department:

Faculty of Electrical Engineering, University of Belgrade
Address: Bulevar Kralja Aleksandra 73, 11000 Belgrade, Serbia
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E-mail: potkonjak@yahoo.com

Citizenship: Serbia

HIGHER EDUCATION

- 1974 University of Belgrade, **Dipl.Ing.**, Field: Electrical Engineering
Belgrade, Yugoslavia
- 1977 University of Belgrade, **Magister** (seven academic years), Field: Electrical Engineering
Belgrade, Yugoslavia
- 1981 University of Belgrade, **Dr. / Ph.D.**, Field: Robotics
Belgrade, Yugoslavia

STATEMENT OF INTERESTS

General: fields of *Robotics, Automation, Biomechanics, and Cybernetics*

Specific:

• *Robot Dynamics and CAD.* My early research interests were in dynamic modeling of robots. The problems discussed were rigid body robots, elastic effects in robot joints (elastic transmissions), constrained motion, impact effects, etc. The results in the field of dynamics led to the efforts towards the development of the world-first CAD system for industrial robots. The system included the choice of

mechanical structure and the choice of drives (the system could handle DC motors and hydraulic drives). Later, the problem of contact with the dynamic environment was considered.

- *Redundancy, Biomechanics, Humanoids*. The research in the field of redundant robots resulted in the concept of distributed positioning - a variation of micro/macro manipulation. The concept followed biomechanical principles. It was applied to both industrial robots and humanoid robots. The interests for humanoid robots resulted in the analysis of redundancy resolution in writing and some other humanoid tasks. The research in the field of humanoid robots included the problems of kinematics, dynamics and intelligent control ("human-like" motion and formation of skills). The field of man-machine analogy and the formulation of mathematical models that would be used in both robotics and biomechanics constitute this important topic of my interest. Biomechanics includes a general interest in modeling human motion and behavior.

- *"Active systems"* are also within my interests. The main result is the concept of variable geometry which can be applied to wide class of mechanical systems (robot, road vehicle, constructions, etc.).

- *Education*. Interest in the education in the field of robotics and automation includes teaching, creation of new majors and syllabi and development of laboratories. Special effort is oriented to Computer-Assisted Learning and Distance Learning.

- ◆ Besides the research, I was engaged in *commercial projects*. I headed the development of some industrial robotic systems. I have special interest in the education in the field of automation. For this reason I tried and succeeded to develop some complex laboratory equipment. These devices are now commercially available. New equipment is now being developed. I see this activity promising.

E X P E R I E N C E / C A R E E R

Academic - domestic:

Faculty of Electrical Eng., University of Belgrade, Serbia

1995-present; *Professor*, field: *Robotics*, Department of Control Eng.

1990-1995; *Associate Professor*, field: *Robotics*, Department of Control Eng.

1985-1990; *Assistant Professor*, fields: *Robotics, Mechanics*, Dept. of Control Eng.

1974-1985; *Teaching and research assistant*

Faculty of Electronics, Univ. of Nis, Serbia

1990-1999; *Professor*, field: *Robotics*, Dept. of Automatic Control

Technical Faculty in Cacak, Univ. of Kragujevac, Serbia

1996-1999; *Professor*, field: *Robotics*

Technical College (ex. Polytechnic Academy), Belgrade, Serbia

1989-present; *Professor*, field: *Electrical Engineering*

College of Electrical Engineering and Computer Science, Belgrade, Serbia

2001-present; *Professor*, field: *Mechanics, Cybernetics, Automation*

Academic - foreign:

National Technical University of Athens, Greece

2000, 2002; *Visiting Professor-Researcher*

Intelligent Robotics and Automation Lab., Institute for Comm. and Computer Syst.

The College of Southeastern Europe - The American University of Athens
2000, 2002; *Professor*, fields: *Mathematics, Mechanics, Robotics*

Study visits

National Technical University of Athens, Greece, in 2009.
Institute for Systems and Robotics / Instituto Superior Tecnico, Lisbon, Portugal, in 2010.

Editor:

International Journal of Humanoid Robotics (Publ. World Scientific)
2010-present, *Associate Editor*

Administrative positions:

Board of Governors of Institute “M. Pupin” Group, Belgrade, Serbia.
2005-2008; *President* of the Board
2008-present; *Member* of the Board

Board of Governors of the Institute for Education Quality and Evaluation, Ministry of
Education, Republic of Serbia.
2005-present; *Member* of the Board

Expert:

Council for technological development of the Republic of Serbia, Belgrade
1989-1991; Member of the expert group for *Robotics*

Ministry of Education, Republic of Serbia
1989-1991; Member of the expert group for elaboration of syllabi for vocational education (VET)
in the field of mechanical eng.

City administration of Belgrade
2006-2008; Member of the commission for the annual award in the field of innovation.

European Commission, (sci.&tech.)
2006; Evaluator for research projects FP6 (Robotics)

Ministry of Education of Serbia and European Agency for Reconstruction
2006-2007; Expert-consultant for the introduction of Mechantronics in VET schools.

National Council for Education - Serbia, Commission for Accreditation
2007-present; expert-reviewer for accreditation of academic institutions

European Commission, (sci.&tech.)
2009-10; Evaluator and Rapporteur for Calls 1, 2, and 3 of the FP7 Project ECHORD

European Commission, (sci.&tech.)
2009-10; Member of Scientific Council of FP7 Project SEE-ERA.NET PLUS

Ministry of Education, Republic of Serbia; Institute for Advances in Education
2010-2011; President of the commission for reformulation of profiles and elaboration of syllabi
for high-school vocational education in the field of electrical engineering.

Organizations:

- Member of the Serbian Scientific Society, since 1999.
- Member of Academy of Engineering Sciences of Serbia, since 2002.
- Member of Serbian Committee for ETRAN (Electronics, Telecommunication, Computer Science and Automatic Control), Head of Section for Robotics and FMS (1995-present).

P U B L I C A T I O N S

This is a short specification; the complete list of publications is given at the end of CV

(A) Books , monographs and book chapters

- Three research monographs (in English): two of them published by Springer-Verlag in 1982 and 1985; and one published by Kluwer Acad. Publ. in 2003.. One monograph has been translated into Japanese and Chinese.
- Two chapters in Mechanical Systems Design Handbook (CRC Press); in English
- Chapter in book on "digital sports" (Information Science Reference – an imprint of IGI Global); in English
- Five books and textbooks in the field of robotics and automation (in Serbian)
- Editor of conference proceedings and chapters in proceedings.

(B) International journal papers

- 64 papers related to the fields of Robotics, Automation, Biomechanics and Cybernetics.

(B3) Papers in Yugoslav journals

- 3 papers

(C) Papers at international conferences

- 28 papers on international conferences

(D) Papers on Serbian (Yugoslav) conferences

- 25 papers

(E) Papers related to the education in the field of robotics

- 7 journal and conference papers

(F) Other papers

- about 10

(G) M.Sc. and Ph.D. thesis (V.Potkonjak)

1. M.Sc. thesis: "Contribution to the algorithms for mathematical modelling of active mechanisms" (in Serbian), Univ. of Belgrade, Faculty of Electrical Eng., Belgrade (Yu), 1977.
2. D.Sc. thesis: "Computer-oriented method for the design of manipulation robots based on the complete dynamic models", Univ. of Belgrade, Faculty of Electrical Eng., Belgrade (Yu), 1981.

C I T A T I O N

- Results of Prof. Potkonjak's work have been cited more than 250 times (according to Citation Index).
- Biography of Prof. Potkonjak has been presented in *Marquis Who's Who in the World* and *Marquis Who's Who in Science and Engineering*, 2003 and later.
- Biography of Prof. Potkonjak has been presented in *Outstanding Scientists of the 21st Century* (ed. 2007), and in *Top 100 Scientists – 2007* (and later), publ. by International Biographical Centre, Cambridge, England.

REVIEWS WRITTEN

Reviews for journals:

- Automatica (IFAC)
- Computers & Education (Elsevier)
- Dynamics and Stability of Systems
- IEEE Transactions on Robotics and Automation
- IEEE Transactions on Systems, Man and Cybernetics
- IEEE Transactions on Pattern Analysis and Machine Intelligence
- Intelligent and Robotic Systems (Kluwer Academic Publ., now Springer)
- International Journal of Humanoid Robotics (World Scientific publ.)
- International Journal of Precision Engineering and Manufacturing (The Korean Society for Precision Engineering)
- Journal of Forensic Document Examiners
- Mechanism and Machine Theory (IFTOMM)
- Military Technical Review (in Serbian)
- Robotics and Autonomous Systems (Elsevier)
- Robotics and CIM (Elsevier)

Reviews for scientific conferences

- ETAN/ETLAN Conference (Yugoslavia)
- Yugoslav Symposium for Applied Robotics
- Other Yugoslav and International conferences

Reviews for projects financed by:

- The Yugoslav Technological Development Fund
- The Serbian Technological Development Fund
- FP6 and FP7 European research program

Reviews for research monographs, books and textbooks in Yugoslavia - about ten.

PROFESSIONAL EXPERIENCE

Funded Research Projects:

1- *Redundant Robotic System for Welding in Shipbuilding*

Headed by Veljko Potkonjak

Funded by: Shipbuilding Industry "Split", 1989.

Funds available*: The head plus two engineers-coresearchers, for one year.

2- *Coordination of Local and Regional Motion of Redundant Robots*

Headed by Veljko Potkonjak

Funded by: the Scientific Fund of the Republic of Serbia, 1991-1995.

Funds available: the head plus 2.5 coresearchers, for five years.

3- *Study and Development of Mobile Robot for Construction Works*

Headed by Veljko Potkonjak

Funded by: the Technology Development Fund of the Republic of Serbia with the participation of GOSA Industry, 1991-1993.

Funds available: the head plus 4 coresearchers, for 3 years.

4- *Softwave System for CAD and Control Synthesis of Manipulation Robots*

Headed by Mimir Vukobratovic, participation of Veljko Potkonjak

Funded by: "M.Pupin" Institute, 1981-1985.

5- *Spray-Painting Robot for Construction Works*

Headed by Veljko Potkonjak

Funded by: the Technology Development Fund of the Republic of Serbia together with GOSA Industry, 1993/94.

Funds available: the head plus two coresearchers, for one year.

6- *Koordinated Motion of Industrial Robots*

Headed by Veljko Potkonjak

Funded by: the Scientific Fund of the Republic of Serbia, 1996-2000

Funds available: the head plus two coresearchers, for 5 years.

7- *Simulation and Experimental Platform for Service Robots*

Funded by: the Scientific Fund of the Republic of Serbia, 2002-2005

Headed by Miomir Vukobratovic, participation of Veljko Potkonjak

8- *Diagnostics Equipment for Visuo-Motoric Coordination Disorders*

Funded by: the Scientific Fund of the Republic of Serbia, 2002-2005

Participation of Veljko Potkonjak

9- *Development of a High-Performance Humanoid Robot*

Funded by: the Scientific Fund of the Republic of Serbia, 2006-2007

Participation of Veljko Potkonjak

10- *Humanoid Robotic Systems – Theory and Application*

Funded by: the Scientific Fund of the Republic of Serbia, 2008-2009

Participation of Veljko Potkonjak

11- *Embodied Cognition in a Compliantly Engineered Robot* (Collaborative Project)

Local heading (partner) – V. Potkonjak

Funded by: European Commission - FP7, 2009-2011

Local funds available: the head plus two coresearchers, for 3 years (260,000 EUR)

12- *Research and Development of Ambient-Intelligent Service Robots with Anthropomorphic Characteristics*

Coordinator – V. Potkonjak

Funded by: the Scientific Fund of the Republic of Serbia, 2011-2014

Funds available: the head plus 17 coresearchers, for 4 years.

 * Available funds are not expressed in the amount of money but in the amount of work. This is more appropriate when you consider the projects done in Yugoslavia/Serbia.

Other Funded Projects:

1- *Automation and Robotics in Vocational Education and Training*

Headed by V. Potkonjak

Ministry of Education and Sports Republic of Serbia; Vocational Education and Training Reform Program – An EU Funded project managed by the European Agency for Reconstruction (CARDS Program), February-November 2005, Budget 57,200 EUR.

Commercial Projects:

1- *PC-based Controller plus Data Acquisition System UK/AP-L-01 for Education and Lab. Application*

Idea by V. Potkonjak. Design and manufacturing headed by V. Potkonjak.

Project was done during 1996 and 1997. Commercial exploitation 1997-2002.

2- *Rotating Table OS-L-01 for Education and Laboratory Application*

Idea by V. Potkonjak. Design and manufacturing headed by V. Potkonjak.

Project was done during 1996. Commercial exploitation 1997-2002.

3- *SCARA for Education and Laboratory Application (SCARA-L-01): mechanical construction plus PC-based controller.*

Project was done during 1997 and 1998.

4- *Laboratory equipment for the exercises and testing in the field of electrical machines*

Idea by V. Potkonjak. Design and manufacturing headed by V. Potkonjak.

Project was done during 1998-1999.

Consulting Activities:

1 - Inovative Solutions (Inos) - Germany, 2000.

- Study: "Torque/Force Sensors and Compliance: Technology, State-of-the-Art, Prospects, and Business Possibilities".

- Study: "Non-Haptic and Haptic Manual Control Systems: Technology, State-of-the-Art, Prospects, and Business Possibilities".

2 - Polytechnic Academy, Belgrade, Serbia

- Study and project of the reform of Technical College: new majors and syllabi, 2002

- Project of the LEGO Robotics Laboratory, 2003

3 – College of Mechanical Engineering, Zemun, Belgrade, Serbia, 2002

- Project of the Laboratory for CNC systems

4 – College of Electrical Eng., Belgrade, Serbia

- Study: Introducing Mechatronics – new curriculum and syllabi, 2003

- Project of the Laboratory for Automatic Control, 2004

Other Activities:

- Representative for products of INTELITEK (Eshed Robotec) and EMCO for Serbia and Montenegro, 2002-2004.

Seminars and conferences:

- Head of organizing committee, Seminar on Robotics and FMS, Ship building Industry "Split", Split, 1988.

- Member of the steering committee of ECPD Conf. on Robotics, 1996. (Vienna), 1997. (Bremen), 1998. (Moscow)

- Member of the International Program Committee of European Workshop on Service and Humanoid Robots (SERVICEROB-2001), June 24-27, 2001. (Santorini, Greece)

- Member of the Program Committee of the 12th Biennial Conference of the International Graphonomics Society (IGS2005), June 26-29, 2005. (Salerno, Italy)

- Member of the Programme Committee of the Intl. Conf. on Computational Vision and Robotics (ICCV 2010), August 21-22, 2010. (Bhubaneswar, India)

- etc.

A W A R D S

- Award "Nikola Tesla" (in a group of five scientists), Contribution to the science, Tesla Foundation, 1985.

- ETAN Award, Best research paper in the field of Robotics and FMS on the Yugoslav Conference on Electronics, Telecommunication, Computers, and Automatics, 1984.

- Belgrade Award (in a group of four scientists), 2003.
- ETRAN Award for the contribution to science in the field of Robotics and FMS, 2006.

TEACHING ACTIVITIES

Faculty of Electrical Eng., University of Belgrade

- Formerly:
- Mechanics*, II year undergraduate
 - Mathematics*, II year undergraduate
 - Physics*, I year undergraduate
 - Technical Drawing*, I year undergraduate
 - Robot Dynamics*, graduate course
 - Flight Dynamics*, graduate course
 - Inertial Navigation Sensors*, graduate course
 - Robot Design and Application*, graduate course
 - Special Robotic Systems*, V year undergraduate
 - Manufacturing Automation*, V year undergraduate
- Currently:
- Dynamics of Mechanical Systems*, II year undergraduate
 - Mechanics*, II year undergraduate
 - Hydraulic and Pneumatic Control Systems*, III year undergraduate
 - Robotics and Automation*, III year undergraduate
 - CNC Systems and Flexible Automation*, IV year undergraduate
 - Biomechanics*, IV year undergraduate
 - Theory of Robotic Systems*, IV year undergraduate, and a graduate course
 - Robot Sensors*, IV year undergraduate, and a graduate course
 - Hydraulic Actuators and Control*, graduate course
 - Special Robotic Systems*, course on Ph.D. studies
 - Theory of Robotic Systems*, course on Ph.D. studies

Faculty of Electronics, University of Nis

- Formerly:
- Dynamics of Robots and Machines*, IV year undergraduate
 - Technical Robotics*, V year undergraduate
 - Control of Robots*, graduate course

Technical Faculty, University of Kragujevac (Cacak)

- Formerly:
- Technical Robotics*, V year undergraduate

Polytechnic Academy, Dept. for Mechanical Eng. , Belgrade

- Formerly:
- Electrical Engineering*
 - Sensors and Actuators*
- Currently:
- Flexible Manufacturing Systems*
 - Robotics*

The College of Electrical Engineering and Computer Science, Belgrade

- Formerly:
- Automatic Control*
 - Cybernetics*
- Currently:
- Mechanics*
 - Flexible manufacturing systems*

The College of Southeastern Europe - The American University of Athens

- 2000, 2002:
- Multivariate Calculus*, undergraduate
 - Analytical Mechanics*, undergraduate/graduate
 - Robotics*, undergraduate/graduate

T H E S I S A N D D I S S E R T A T I O N S

Ph.D. thesis supervisor

Mugdim Pasic, University of Sarajevo, 1992.
 Goran Djordjevic, University of Nis, 1995.
 Petar Maric, University of Banja Luka, 1999.
 Mihajlo Lazarevic, University of Belgrade, 1999.
 Mirjana Filipovic, University of Belgrade, 2007.
 Milos Jovanovic, University of Belgrade, *present*
 Vesna Antoska, University of Skopje, *present*

Magister thesis (after seven university years) supervisor

Goran Djordjevic, Faculty of Electronics, Nis, 1992.
 Ljubinko Janjusevic, Faculty of Electrical Eng., Belgrade, 1999.
 Zeyad Hamza Shennib, Faculty of Electrical Eng., Belgrade, 2000.
 Salem Arbi Shafat, Faculty of Electrical Eng., Belgrade, 2000.
 Jamal O.S. Bagni, Faculty of Electrical Eng., Belgrade, 2000.
 Walid Mabruk Allaghi, Faculty of Electrical Eng., Belgrade, 2000.
 Dragan Kostic, Faculty of Electronics, Nis, 2000.
 Ivan Pavlovic, Center for Multidisciplinary Studies, Univ. of Belgrade, 2003.
 Jelena Radojicic, Faculty of Electrical Eng, Belgrade, 2004.
 Tarek Muhamed Abugamja, Faculty of Electrical Eng, Belgrade, 2004.
 Milos Jovanovic, Faculty of Electrical Eng, Belgrade, 2004.
 Ramadan Ali Isa Abouisha, Faculty of Electrical Eng, Belgrade, 2005.
 Milena Petrovic, Faculty of Electrical Eng, Belgrade, 2009.
 Milos Bojanic, Faculty of Electrical Eng, Belgrade, 2010.

M.Sc. thesis (after five university years) supervisor

Bratislav Svetozarevic, Faculty of Electrical Eng, Belgrade, 2009.
 Kosta Jovanovic, Faculty of Electrical Eng, Belgrade, 2010.
 Vanja Komadinovic, Faculty of Electrical Eng, Belgrade, 2010.

Ph.D. thesis, member of the Committee

A large number

Magister and M.Sc. thesis, member of the Committee

A large number

B.Sc. thesis supervisor - a large number.

P U B L I C A T I O N S – The Complete List

(A) Books , monographs and book chapters

Monograph books:

1. M. Vukobratovic, V. Potkonjak, Dynamics of Manipulation Robots, Springer-Verlag, Berlin, (1982), (320 pages).
 - 1a. This monograph was translated into Japanese. The book was published in Japan in 1986.
 - 1b. The monograph was translated into Chinese (1990).
 - 1c. Serbian language version appeared in 1981.
2. M. Vukobratovic, V. Potkonjak, Applied Dynamics and CAD of Manipulation Robots, Springer-Verlag, Berlin, (1985), (305 pages).
3. M. Vukobratovic, V. Potkonjak, V. Matijevic, Dynamics of Robots with Contact Tasks, Kluwer Academic Publishers, (2003), (248 pages).

Book chapters:

4. M. Vukobratovic, V. Potkonjak, Chapter 20: Dynamics, in Section: Robotics, Mechanical Systems Design Handbook, CRC Press, 2001.
5. M. Vukobratovic, V. Potkonjak, K. Inoue, M. Takano, Chapter 21: Actuators and CAD of Robots, in Section: Robotics, Mechanical Systems Design Handbook, CRC Press, 2001.
6. V. Potkonjak, M. Vukobratovic, K. Babkovic, B. Borovac, Chapter: Dynamics and Simulation of General Human and Humanoid Motion in Sports, in Nigel Pope's (Editor) book: Digital Sport for Performance Enhancement and Competitive Evolution: Intelligent Gaming Technologies, Information Science Reference (an imprint of IGI Global), USA, May 2009.

Text books:

7. V. Potkonjak, Advanced Robots (in Serbian), Tehnicka knjiga (Technical books), Beograd (1986), (183 pages).
8. V. Potkonjak, Robotics, (in Serbian) Naucna knjiga (Scientific books), Beograd, (1989), Univ. of Belgrade (1996), (292 pages).
9. V. Potkonjak, Elements of Automation and Robotics (in Serbian), Zavod za izdavanje udzbenika (Textbook publ. comp.), Belgrade, 1993, (150 pages).
10. V. Potkonjak et.al., Flexible Automation (in Serbian), Zavod za izdavanje udzbenika (Textbook publ. comp.), Belgrade, 1993, (320 pages).
11. M. Bucan, M. Milojevic, V. Potkonjak, Manufacturing Automation (in Serbian), Zavod za izdavanje udzbenika (Textbook publ. comp.), Belgrade, 2000, (284 pages).

As Editor:

12. A. Kecskemethy, V. Potkonjak (editors), Proc. of intl. conf. Interdisciplinary Applications of Kinematics, Lima, Peru, January 9-11, 2008.
- 13.1 - 13.6 V. Potkonjak (editor), Chapter: Robotics, in Proc. of ETRAN, 1995–present (annual conference).

(B1) Invited papers in international journals

1. D.Milutinovic, V.Potkonjak, "A New Concept of the SCARA Robot", Robotics and Computer-Integrated Manufacturing (Pergamon Press), Vol. 7, No. 3/4, pp. 337-343, 1990.

(B2) International journal papers

2. M.Vukobratovic, V.Potkonjak, "Contribution to the Forming of Computer Methods for Automatic Modelling of Spatial Mechanisms Motions", PARTI. "Method of Basic Theorems of Mechanics", IFToMM Journal of Mechanisms and Mechine Theory, Vol.14, No.3, pp.179-188, (1979).
3. V.Potkonjak,M.Vukobratovic, "Two New Methods for Computer Forming of Dynamic Equations of Active Mechanisms", Journal of Mechanisms and Machine Theory, Vol.14, No.3, pp.189-200, (1979).
4. M.Vukobratovic, V.Potkonjak, (in Russian) "Nekomopbie vi~islitelbnie metodi modelirovanija na EVM dinamiki aktivnih prostranstvenih mehanizmov", ANU SSSR, Tehni~eskaja kibernetika, No.1, Moskva, pp.52-60, (1979).
5. M.Vukobratovic, V.Potkonjak, "Contribution to Computer Con struction of Active Chain Models Via Lagrangian Form", Journal of Applied Mechanics -Trans. of the ASME, No.1, Vol.46, pp.181-185, (1979).
6. V.Potkonjak, M.Vukobratovic, "CAD of Manipulation Robots Via Multi-Parameters Optimization", Journ. of Mech. and Mach. Theory, Vol.18, No.6, pp.431-438, (1983).
7. V.Potkonjak, N.Jaksic, "Contribution to the Computer-Aided Choice of D.C.Motors for Manipulation Robots", Robotica (Cambridge University Press), Vol.4, pp.37-41, (1986).
8. V.Potkonjak, M.Vukobratovic, "Dynamics of Manipulation Mechanisms with Constrained Gripper Motion", Journal of Robotic Systems (John Wiley), 3(3) pp.321-334, (1986).
9. M.Vukobratovic, V.Potkonjak, "Constrained Gripper Motion in Assembly Manipulation", Journal of Robotic Systems, 3(3), pp.335-347, (1986).
10. M.Vukobratovic, D.Katic, V.Potkonjak, "Computer-Assisted Choice of Electrohydraulic Servosystems for Manipulation Robots Usig Complete Mathematical Models", Journal of Mechanisms and Machine Theory, Vol.22, No.5, pp.431-439, 1987.
11. V.Potkonjak, "Contribution to the Dynamics and Control of Robots Having Elastic Transmissions", Robotica, Vol.6, pp.63-69, (1988).

12. V.Potkonjak, "Contribution to the Analysis of Elastic Oscillations of Controlled Articulated Systems", *Robotics and Computer-Integrated Manufacturing* (Pargamon Press), Vol.5, No.2/3, pp.123-128, (1989).
13. V.Potkonjak, "Thermal Analysis and Dynamic Capabilities of D.C. Motors in Industrial Robotic Systems", *Intl.J. of Robotics and Computer-Integrated Manufacturing*, Vol.5, No.2/3, pp.137-143, (1989).
14. V.Potkonjak, "Distributed Positioning for Redundant Robotic Systems", *Robotica*, Vol.8, No.1, pp.61-67, (1990).
15. V.Potkonjak, A.Krstulovic, "Improvement of Dynamic Capabilities of Heavy Robots", *Robotica*, Vol. 8/3, pp. 217-222, 1990.
16. V.Potkonjak, "New Approach to the Application of Redundant Robots", *Intl.J.Robotics and Computer-Integrated Manufacturing*, Vol.8, No. 3, pp. 181-185, 1991.
17. V.Potkonjak, A.Krstulovic, "Robotic Welding System With Parallel Degrees of Freedom", *Robotics and Computer-Integrated Manufacturing*, Vol. 8, No. 3, pp.171-174, 1991.
18. V.Potkonjak, A.Krstulovic, "Contribution to the Kinematics and Dynamics of Redundant Robots Via Distributed Positioning", *Journal of Intelligent and Robotic Systems* (Kluwer Academic Publishers) 5, pp. 229-239, 1992.
19. V.Potkonjak, A.Krstulovic, "Mathematical Modelling of a Redundant Antropomorphic Arm", *Robotics and Autonomous Systems* (Elsevier) 9, pp. 165-170, 1992.
20. V.Potkonjak, A.Krstulovic, "Simulation of a Redundant Antropomorphic Arm", *Robotics and Autonomous Systems* (Elsevier) 9, pp. 171-179, 1992.
21. V.Potkonjak, "Application of Redundant Robots to Constrained-Motion Tasks", *Robotica*, Vol. 10, pp. 397-407, 1992.
22. V.Drenovac, V.Potkonjak, "Contribution to the Modelling of Impact with Robotic Systems", *Robotica*, Vol. 11/5, pp. 445-452, 1993.
23. V.Potkonjak, G.Djordjevic, C.Milosavljevic, D.Antic, "Variable Structure Systems for Control of Redundant Robot", *Robotics and Autonomous Systems*, 13, pp.13-24, 1994.
24. V.Potkonjak, T.Petrovic, "Contribution to Robot Control with Parallel Degrees of Freedom", *Robotica*, Vol. 12, Part 6, pp. 569-573, 1994.
25. V.Potkonjak, G.Djordjevic, C.Milosavljevic, D.Antic, D.Popovic, "Kinematic Redundancy and Sensor Redundancy for Enhancement of Robot Tracking Performances", *Journal of Intelligent and Robotic Systems*, 15, pp. 263-289, 1996.
26. I. Miljakovic-Jeftic, V. Potkonjak, "Secondary School Specialization in Robotics and FMS : A Practical Experience (a viewpoint)", *Robotica*, Vol. 14, pp. 451-455, 1996.
27. V. Potkonjak, G. Djordjevic, C. Milosavljevic, D. Antic, "Design of Tactical and Executive Level of Redundant Robot Control Via Distributed Positioning", *International Journal of Robotics & Automation (IASTED)*, Vol. 11, Issue 3, pp. 102-110, 1996.
28. M. Vukobratovic, V. Potkonjak, "Dynamics of Free and Constrained Motion of Robots and Robotized Systems", Part I: "General Approach to System Dynamics and Coupling of Subsystems", *Intl. J. Engineering & Automation Problems* (Intl. Centre for Scientific and Technical Informations, Moscow), No. 3-4, pp. 3-9, 1997.
29. V. Potkonjak, M. Vukobratovic, "Dynamics of Free and Constrained Motion of Robots and Robotized Systems", Part II: "Dynamics of Robotized Industrial Systems", *Intl. J. Engineering & Automation Problems* (Intl. Centre for Scientific and Technical Informations, Moscow), No. 5-6, pp. 5-14, 1997.
30. M. Vukobratovic, V. Potkonjak, "Dynamics of Contact Tasks in Robotics. Part I: General Model of Robot Interacting with Environment", *Mechanism and Machine Theory* 34, pp.923-942, 1999.
31. V. Potkonjak, M. Vukobratovic, V. Matijevec, "Dynamics of Contact Tasks in Robotics. Part II: Case-Study in Dynamics of Constrained Motion", *Mechanism and Machine Theory* 34, pp. 943-972, 1999.
32. V. Potkonjak, M. Popovic, M. Lazarevic, J. Sinanovic, "Redundancy Problem in Writing: From Human to Anthropomorphic Robot Arm", *IEEE Transactions on SMC, Part B: Cybernetics*, Vol. 28, No. 6, pp. 790-805, Dec. 1998.
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(F) Other papers

V. Potkonjak has published about 10 papers which are not mentioned in this list.